

# UT54LVDS031LV/E Low Voltage Quad Driver

Data Sheet

October, 2004

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## FEATURES

- ❑ >400.0 Mbps (200 MHz) switching rates
- ❑  $\pm 340\text{mV}$  nominal differential signaling
- ❑ 3.3 V power supply
- ❑ TTL compatible inputs
- ❑ Cold sparing all pins
- ❑ Ultra low power CMOS technology
- ❑ 1.5ns maximum, propagation delay
- ❑ 310ps maximum, differential skew
- ❑ Radiation-hardened design; total dose irradiation testing to MIL-STD-883 Method 1019
  - Total-dose: 300 krad(Si) and 1Mrad(Si)
  - Latchup immune (LET > 100 MeV-cm<sup>2</sup>/mg)
- ❑ Packaging options:
  - 16-lead flatpack (dual in-line)
- ❑ Standard Microcircuit Drawing 5962-98651
  - QML Q and V compliant part

## INTRODUCTION

The UT54LVDS031LV Quad Driver is a quad CMOS differential line driver designed for applications requiring ultra low power dissipation and high data rates. The device is designed to support data rates in excess of 400.0 Mbps (200 MHz) utilizing Low Voltage Differential Signaling (LVDS) technology.

The UT54LVDS031LV accepts low voltage TTL input levels and translates them to low voltage (340mV) differential output signals. In addition, the driver supports a three-state function that may be used to disable the output stage, disabling the load current, and thus dropping the device to an ultra low idle power state.

The UT54LVDS031LV and companion quad line receiver UT54LVDS032LV provide new alternatives to high power pseudo-ECL devices for high speed point-to-point interface applications.

All pins have Cold Spare buffers. These buffers will be high impedance when  $V_{DD}$  is tied to  $V_{SS}$ .

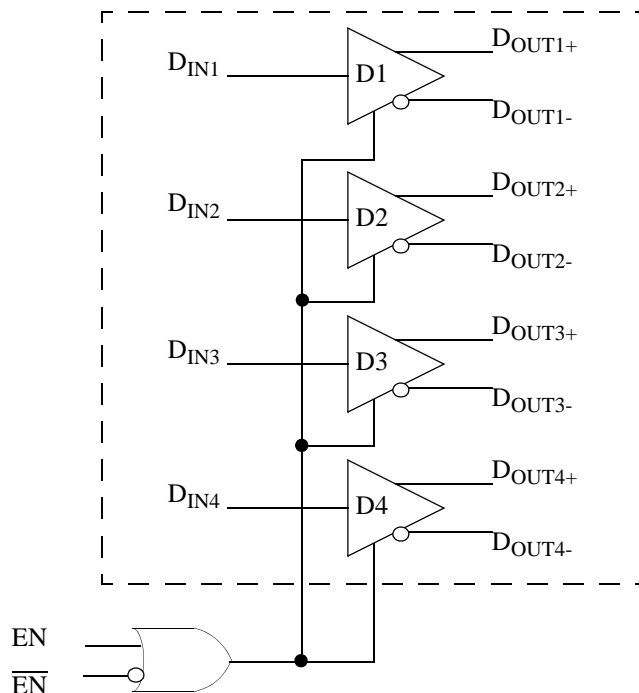
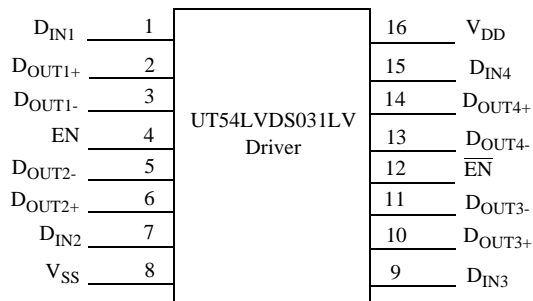


Figure 1. UT54LVDS031LV Quad Driver Block Diagram



**Figure 2. UT54LVDS031LV Pinout**

## TRUTH TABLE

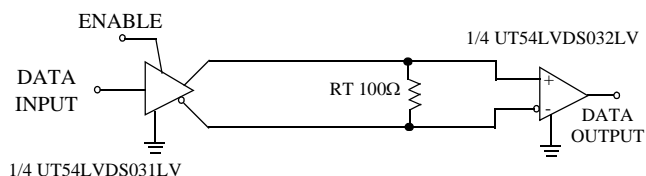
Enables		Input	Output	
EN	$\overline{\text{EN}}$	D <sub>IN</sub>	D <sub>OUT+</sub>	D <sub>OUT-</sub>
L	H	X	Z	Z
All other combinations of ENABLE inputs		L	L	H
		H	H	L

## PIN DESCRIPTION

Pin No.	Name	Description
1, 7, 9, 15	D <sub>IN</sub>	Driver input pin, TTL/CMOS compatible
2, 6, 10, 14	D <sub>OUT+</sub>	Non-inverting driver output pin, LVDS levels
3, 5, 11, 13	D <sub>OUT-</sub>	Inverting driver output pin, LVDS levels
4	EN	Active high enable pin, OR-ed with $\overline{\text{EN}}$
12	$\overline{\text{EN}}$	Active low enable pin, OR-ed with EN
16	V <sub>DD</sub>	Power supply pin, +3.3V $\pm$ 0.3V
8	V <sub>SS</sub>	Ground pin

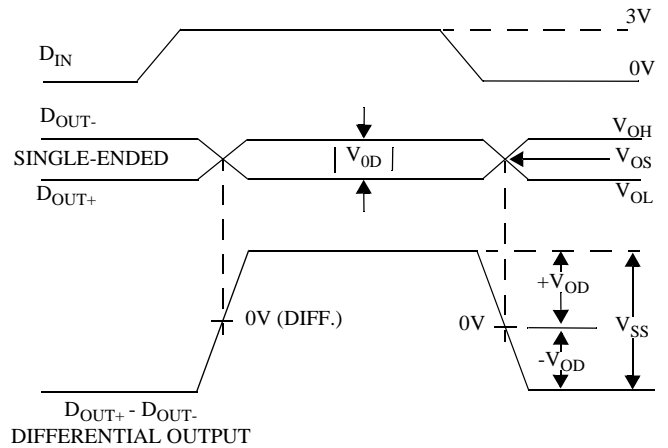
## APPLICATIONS INFORMATION

The UT54LVDS031LV driver's intended use is primarily in an uncomplicated point-to-point configuration as is shown in Figure 3. This configuration provides a clean signaling environment for quick edge rates of the drivers. The receiver is connected to the driver through a balanced media such as a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically, the characteristic impedance of the media is in the range of 100Ω. A termination resistor of 100Ω should be selected to match the media and is located as close to the receiver input pins as possible. The termination resistor converts the current sourced by the driver into voltages that are detected by the receiver. Other configurations are possible such as a multi-receiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities, as well as ground shifting, noise margin limits, and total termination loading must be taken into account.



**Figure 3. Point-to-Point Application**

The UT54LVDS031LV differential line driver is a balanced current source design. A current mode driver, has a high output impedance and supplies a constant current for a range of loads (a voltage mode driver on the other hand supplies a constant voltage for a range of loads). Current is switched through the load in one direction to produce a logic state and in the other direction to produce the other logic state. The current mode **requires** (as discussed above) that a resistive termination be employed to terminate the signal and to complete the loop as shown in Figure 3. AC or unterminated configurations are not allowed. The 3.4mA loop current will develop a differential voltage of 340mV across the 100Ω termination resistor which the receiver detects with a 240mV minimum differential noise margin neglecting resistive line losses (driven signal minus receiver threshold (340mV - 100mV = 240mV)). The signal is centered around +1.2V (Driver Offset, V<sub>OS</sub>) with respect to ground as shown in Figure 4. **Note:** The steady-state voltage (V<sub>SS</sub>) peak-to-peak swing is twice the differential voltage (V<sub>OD</sub>) and is typically 680mV.



Note: The footprint of the UT54LVDS031LV is the same as the industry standard Quad Differential (RS-422) Driver.

**Figure 4. Driver Output Levels**

The current mode driver provides substantial benefits over

SYMBOL	PARAMETER	LIMITS
$V_{DD}$	DC supply voltage	-0.3 to 4.0V
$V_{I/O}$	Voltage on any pin during operation	-0.3 to ( $V_{DD} + 0.3V$ )
	Voltage on any pin during cold spare	-.3 to 4.0V
$T_{STG}$	Storage temperature	-65 to +150°C
$P_D$	Maximum power dissipation	1.25 W
$T_J$	Maximum junction temperature <sup>2</sup>	+150°C
$\Theta_{JC}$	Thermal resistance, junction-to-case <sup>3</sup>	10°C/W
$I_I$	DC input current	±10mA

**Notes:**

1. Stresses outside the listed absolute maximum ratings may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions beyond limits indicated in the operational sections of this specification is not recommended. Exposure to absolute maximum rating conditions for extended periods may affect device reliability and performance.
2. Maximum junction temperature may be increased to +175°C during burn-in and life test.
3. Test per MIL-STD-883, Method 1012.

**RECOMMENDED OPERATING CONDITIONS**

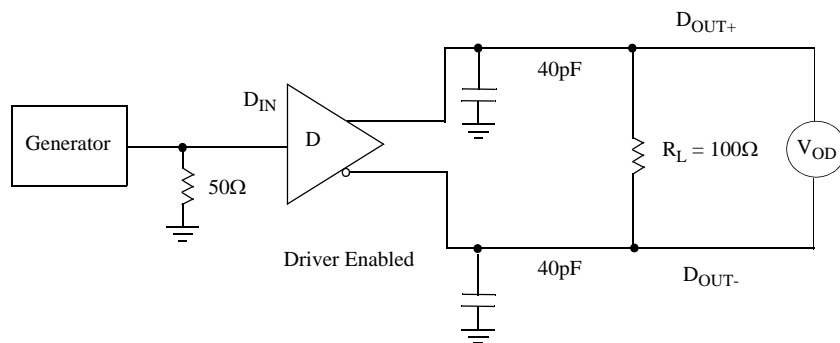
<b>SYMBOL</b>	<b>PARAMETER</b>	<b>LIMITS</b>
$V_{DD}$	Positive supply voltage	3.0 to 3.6V
$T_C$	Case temperature range	-55 to +125°C
$V_{IN}$	DC input voltage	0V to $V_{DD}$

**DC ELECTRICAL CHARACTERISTICS<sup>1, 2</sup>**  
**( $V_{DD} = 3.3V \pm 0.3V$ ;  $-55^{\circ}C < T_C < +125^{\circ}C$ )**

SYMBOL	PARAMETER	CONDITION	MIN	MAX	UNIT
$V_{IH}$	High-level input voltage	(TTL)	2.0	$V_{DD}$	V
$V_{IL}$	Low-level input voltage	(TTL)	$V_{SS}$	0.8	V
$V_{OL}$	Low-level output voltage	$R_L = 100\Omega$	0.925		V
$V_{OH}$	High-level output voltage	$R_L = 100\Omega$		1.650	V
$I_{IN}$	Input leakage current	$V_{IN} = V_{DD}$ or GND, $V_{DD} = 3.6V$	-10	+10	$\mu A$
$I_{CS}$	Cold Spare Leakage Current	$V_{IN}=3.6V$ , $V_{DD}=V_{SS}$	-20	+20	$\mu A$
$V_{OD}^1$	Differential Output Voltage	$R_L = 100\Omega$ (figure 5)	250	400	mV
$\Delta V_{OD}^1$	Change in Magnitude of $V_{OD}$ for Complementary Output States	$R_L = 100\Omega$ (figure 5)		35	mV
$V_{OS}$	Offset Voltage	$R_L = 100\Omega$ ( $V_{OS} = \frac{V_{oh} + V_{ol}}{2}$ )	1.125	1.450	V
$\Delta V_{OS}$	Change in Magnitude of $V_{OS}$ for Complementary Output States	$R_L = 100\Omega$ (figure 5)		25	mV
$V_{CL}^3$	Input clamp voltage	$I_{CL} = +18mA$	-1.5		V
$I_{OS}^{2, 3}$	Output Short Circuit Current	$V_{IN} = V_{DD}$ , $V_{OUT+} = 0V$ or $V_{IN} = GND$ , $V_{OUT-} = 0V$		9.0	mA
$I_{OZ}^3$	Output Three-State Current	$EN = 0.8V$ and $\overline{EN} = 2.0V$ , $V_{OUT} = 0V$ or $V_{DD}$ , $V_{DD} = 3.6V$	-10	+10	$\mu A$
$I_{CCL}^3$	Loaded supply current, drivers enabled	$R_L = 100\Omega$ all channels $V_{IN} = V_{DD}$ or $V_{SS}$ (all inputs)		18.0	mA
$I_{CCZ}^3$	Loaded supply current, drivers disabled	$D_{IN} = V_{DD}$ or $V_{SS}$ $EN = V_{SS}$ , $\overline{EN} = V_{DD}$		3.0	mA

**Notes:**

1. Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except differential voltages.
2. Output short circuit current ( $I_{OS}$ ) is specified as magnitude only, minus sign indicates direction only.
3. Guaranteed by characterization.



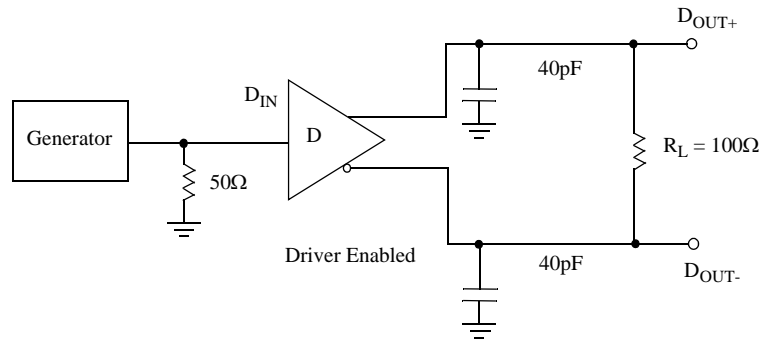
**Figure 5. Driver  $V_{OD}$  and  $V_{OS}$  Test Circuit or Equivalent Circuit**

**AC SWITCHING CHARACTERISTICS<sup>1, 2, 3</sup>**(V<sub>DD</sub> = +3.3V ± 0.3V, T<sub>A</sub> = -55 °C to +125 °C)

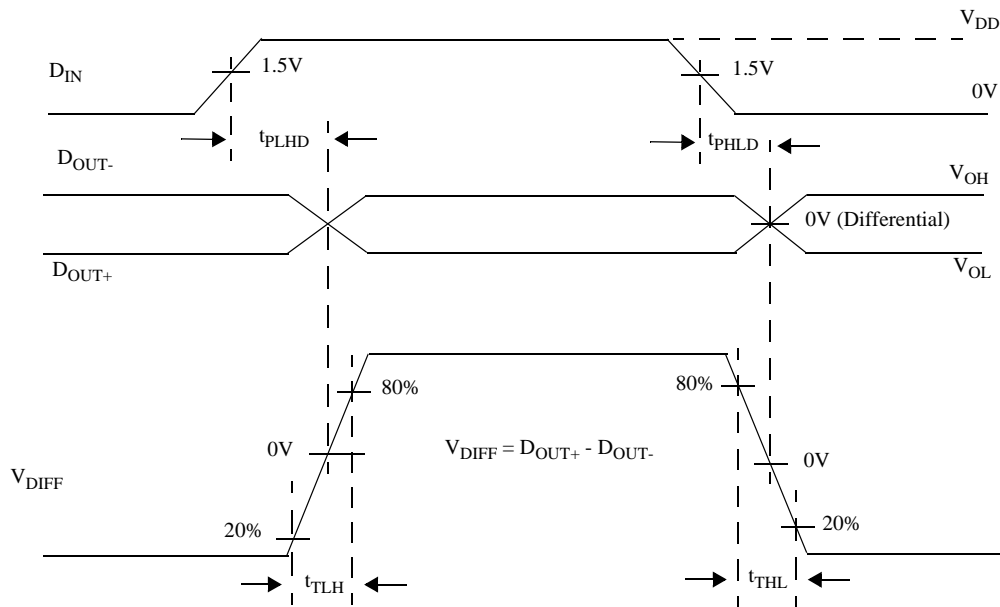
SYMBOL	PARAMETER	MIN	MAX	MIN	MAX	UNIT
		UT54LVDS031LV		UT54LVDS031LVE		
t <sub>PHLD</sub>	Differential Propagation Delay High to Low (figures 6 and 7)	0.3	3.0	0.8	1.5	ns
t <sub>PLHD</sub>	Differential Propagation Delay Low to High (figures 6 and 7)	0.3	3.0	0.8	1.5	ns
t <sub>SKD</sub>	Differential Skew (t <sub>PHLD</sub> - t <sub>PLHD</sub> ) (figures 6 and 7)	0	400	0	310	ps
t <sub>SK1</sub>	Channel-to-Channel Skew <sup>1</sup> (figures 6 and 7)	0	500	0	280	ps
t <sub>SK2</sub>	Chip-to-Chip Skew <sup>5</sup> (figure 6 and 7)		2.7		700	ps
t <sub>TLH</sub> <sup>4</sup>	Rise Time (figures 6 and 7)		1.5		0.6	ns
t <sub>THL</sub> <sup>4</sup>	Fall Time (figures 6 and 7)		1.5		0.6	ns
t <sub>PHZ</sub>	Disable Time High to Z (figures 8 and 9)		5.0		2.8	ns
t <sub>PLZ</sub>	Disable Time Low to Z (figures 8 and 9)		5.0		2.8	ns
t <sub>PZH</sub>	Enable Time Z to High (figures 8 and 9)		7.0		2.5	ns
t <sub>PZL</sub>	Enable Time Z to Low (figures 8 and 9)		7.0		2.5	ns

**Notes:**

1. Channel-to-Channel Skew is defined as the difference between the propagation delay of the channel and the other channels in the same chip with an event on the inputs.
2. Generator waveform for all tests unless otherwise specified: f = 1 MHz, Z<sub>O</sub> = 50, t<sub>r</sub> ≤ 1ns, and t<sub>f</sub> ≤ 1ns.
3. C<sub>L</sub> includes probe and jig capacitance.
4. Guaranteed by characterization
5. Chip to Chip Skew is defined as the difference between the minimum and maximum specified differential propagation delays.

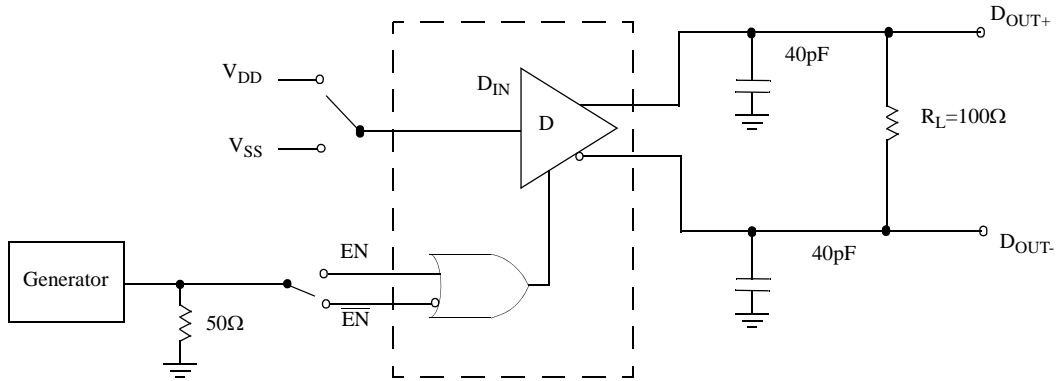


**Figure 6. Driver Propagation Delay and Transition Time Test Circuit or Equivalent Circuit**

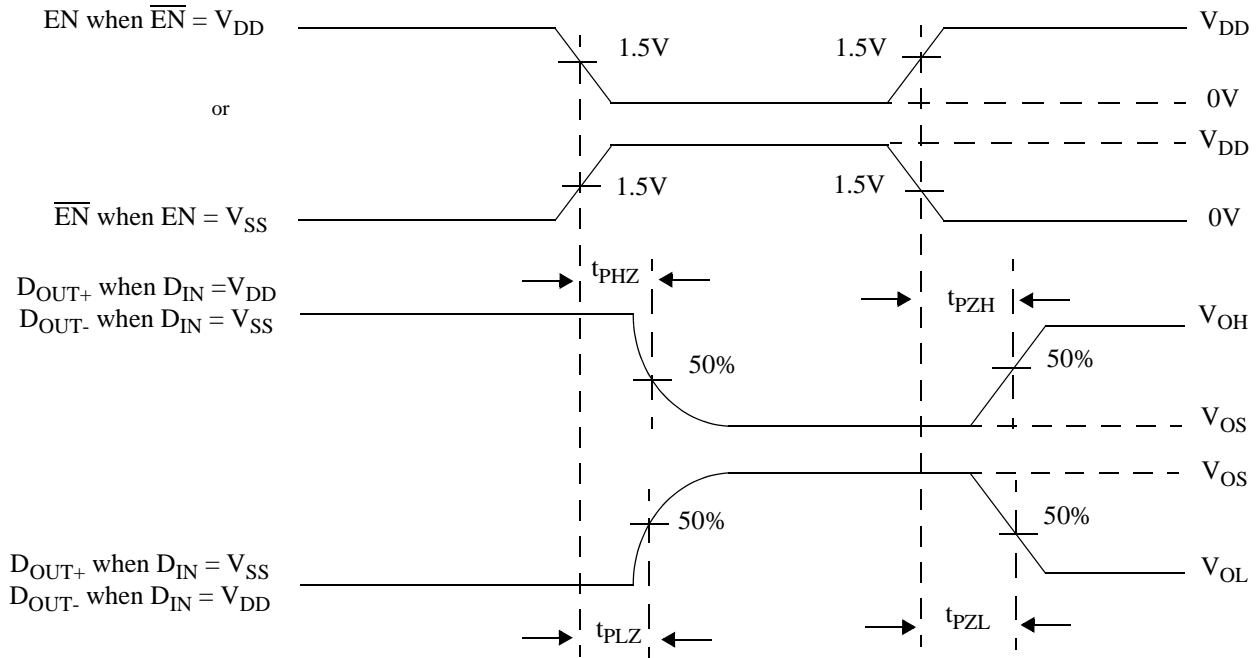


**Figure 7. Driver Propagation Delay and Transition Time Waveforms**



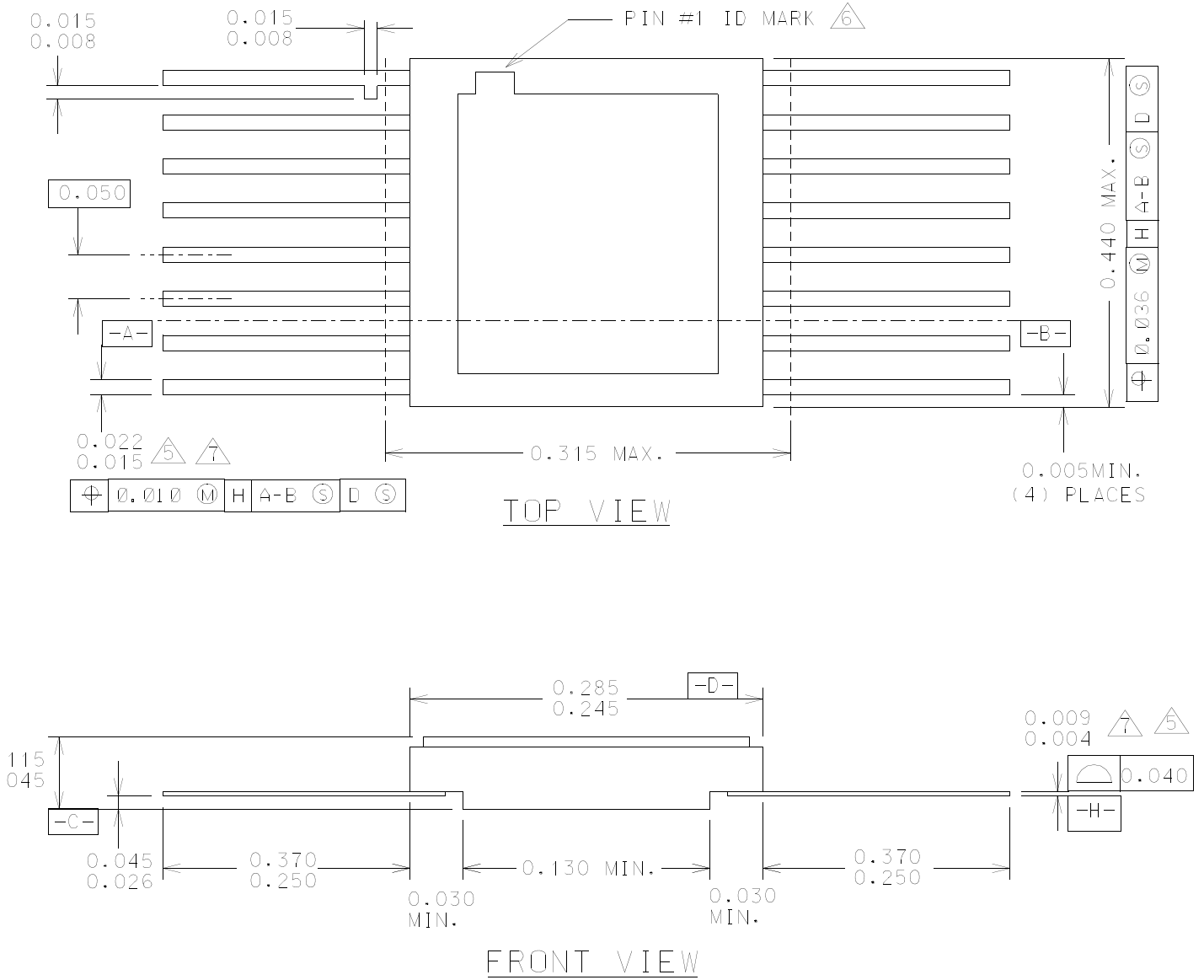


**Figure 8. Driver Three-State Delay Test Circuit or Equivalent Circuit**



**Figure 9. Driver Three-State Delay Waveform**

## PACKAGING



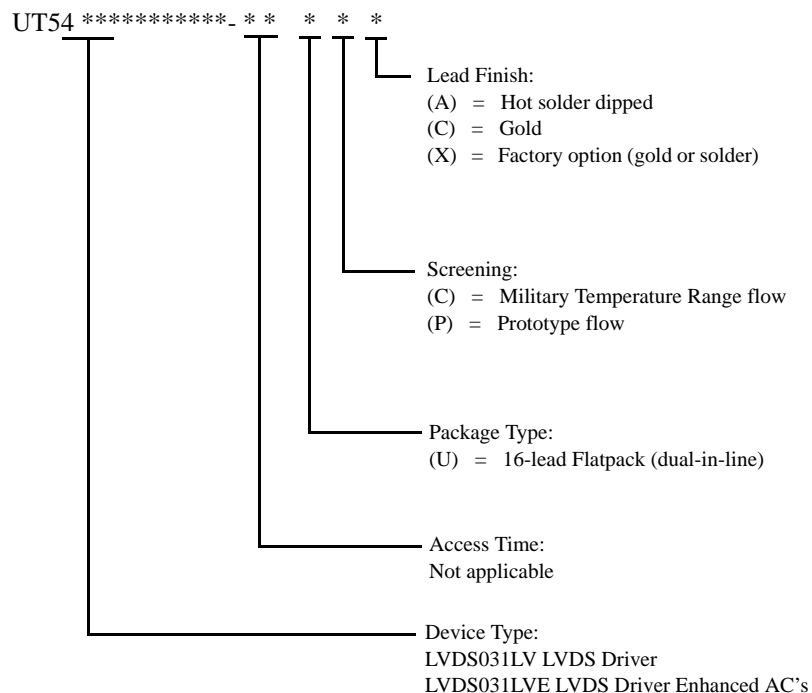
### Notes:

1. All exposed metalized areas are gold plated over electroplated nickel per MIL-PRF-38535.
  2. The lid is electrically connected to VSS.
  3. Lead finishes are in accordance to MIL-PRF-38535.
  4. Package dimensions and symbols are similar to MIL-STD-1835 variation F-5A.
- $\triangle$  Lead position and coplanarity are not measured.
- $\triangle$  ID mark symbol is vendor option.
- $\triangle$  With solder, increase maximum by 0.003.

**Figure 10. 16-pin Ceramic Flatpack**

## ORDERING INFORMATION

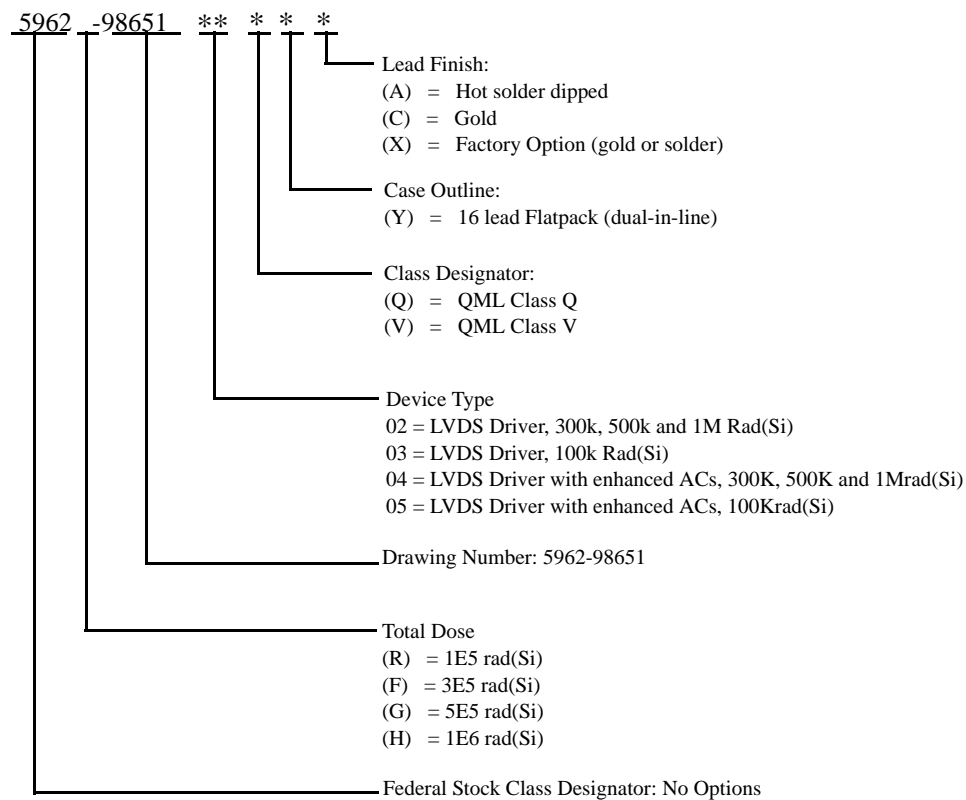
### UT54LVDS031LV/E QUAD DRIVER:



#### Notes:

1. Lead finish (A,C, or X) must be specified.
2. If an "X" is specified when ordering, then the part marking will match the lead finish and will be either "A" (solder) or "C" (gold).
3. Prototype flow per Aeroflex Manufacturing Flows Document. Tested at 25°C only. Lead finish is GOLD ONLY. Radiation neither tested nor guaranteed.
4. Military Temperature Range flow per Aeroflex Manufacturing Flows Document. Devices are tested at -55°C, room temp, and 125°C. Radiation neither tested nor guaranteed.

## UT54LVDS031LV/E QUAD DRIVER: SMD



### Notes:

1. Lead finish (A, C, or X) must be specified.
2. If an "X" is specified when ordering, part marking will match the lead finish and will be either "A" (solder) or "C" (gold).
3. Total dose radiation must be specified when ordering. QML Q and QML V not available without radiation hardening.

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